

Chapter 1

Formal Pushdown Automata

Formal Definition and View

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1.1

Overview

Aim of the Lecture

1. Define pushdown automaton in a formal way
2. Top-down and bottom-up analysis of context-free languages
3. One-turn pushdown automata
4. Atomic pushdown automata

1.2

Contents

1	Introduction	1
2	Formal Definition of PA	2
2.1	Definition	2
2.2	Examples	3
3	Syntax Analysis	4
3.1	Top-Down Analysis	4
3.2	Bottom-Up Analysis	6
4	Deterministic/ Non-Deterministic PA	7
4.1	Non-Deterministic PA	7
4.2	Deterministic PA	8
4.3	Examples	8
5	Modifications of PA	9
5.1	Non-Head-Moving PA	10
5.2	One-Turn PA	12
5.3	Atomic PA	12
6	Conclusion	13

1.3

1 Introduction

What is a *pushdown*?

Merriam-Webster

A store of data (as in a computer) from which the most recently stored item must be the first retrieved—called also *pushdown list* or *pushdown stack*.

We stick to this definition!

1.4

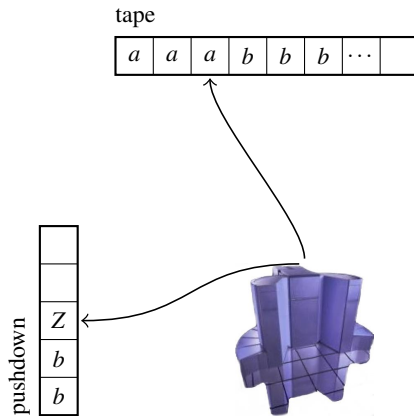
Why do we need them?

- Finite automata handle regular languages only
- Syntax of programming languages is context-free
 - Program text is of arbitrary length
 - Repeated nested bracket-like structures(e.g. arithmetic expressions)
- Pushdown automata offer infinite memory(even if LIFO structure)

1.5

2 Formal Definition of PA

Informal View



1.6

2.1 Definition

Definition of Pushdown Automaton

Formal Definition of Pushdown Automaton

A pushdown automaton is a seven-tuple $M = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$, where

- Q — finite set of states
- Σ — finite input alphabet
- Γ — finite alphabet of pushdown symbols
- δ — mapping $Q \times (\Sigma \cup \{\epsilon\}) \times \Gamma \rightarrow 2^{Q \times \Gamma^*}$ transition function
- $q_0 \in Q$ — starting/initial state
- $Z_0 \in \Gamma$ — start symbol on the pushdown
- $F \subseteq Q$ — set of final states

1.7

Configuration

Definition of Configuration

A configuration of PA M is a triple $(q, w, \alpha) \in Q \times \Sigma^* \times \Gamma^*$, where

- q — current state of the finite control
- w — unused input; the first symbol of w is under the reading head; if $w = \epsilon$, then it is assumed that all the input has been read
- α — contents of the pushdown; the leftmost symbol is the topmost symbol; if $\alpha = \epsilon$, then the pushdown is assumed to be empty

1.8

Move / Transition

Move/Transition Definition

A *move/transition* by M is represented by the binary relation \vdash_M (or \vdash if M is understood) on configurations. We write

$$(q, aw, Z\alpha) \vdash (q', w, \gamma\alpha)$$

if $(q', \gamma) \in \delta(q, a, Z)$ for any $q \in Q$, $a \in \Sigma \cup \{\varepsilon\}$, $w \in \Sigma^*$, $Z \in \Gamma$, and $\alpha \in \Gamma^*$.

We can define relations \vdash^i , $i \geq 0$, \vdash^* , and \vdash^+ in the traditional way. \vdash^* and \vdash^+ stand for reflexive-transitive and transitive closures of \vdash , respectively.

1.9

Final Configuration

- Initial configuration: (q_0, w, Z_0) , $w \in \Sigma^*$
- *Note: from the definition, it follows that there is no move possible if the pushdown is empty.*
- Final configuration, Ξ , $\Xi \in \{1, 2, 3\}$:
 1. Empty pushdown: $(q, \varepsilon, \varepsilon)$, $q \in Q$
 2. Final state: $(q_F, \varepsilon, \alpha)$, $q_F \in F$, $\alpha \in \Gamma^*$
 3. Final state and empty pushdown: $(q_F, \varepsilon, \varepsilon)$, $q_F \in F$

1.10

Accepted Language

- A word w , $w \in \Sigma^*$, is accepted by M if it makes transitions $(q_0, w, Z_0) \vdash^* \Xi$, where $\Xi \in \{1, 2, 3\}$ is the selected final configuration.

Language accepted by M

$L(M) = \{w \mid (q_0, w, Z_0) \vdash^* \Xi\}$, where $\Xi \in \{1, 2, 3\}$ is some (but fixed) of the final configurations.

1.11

2.2 Examples

Example 1 ($a^n b^n$, $n \geq 0$) — Definition

$M = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$

$Q = \{q_0\}$ $\Sigma = \{a, b\}$ $\Gamma = \{a, Z_0\}$ $F = \{q_0\}$

δ : $\delta(q_0, a, Z_0) \rightarrow \{(q_0, Z_0 a)\}$

$\delta(q_0, b, a) \rightarrow \{(q_0, \varepsilon)\}$

$\delta(q_0, \varepsilon, Z_0) \rightarrow \{(q_0, \varepsilon)\}$

1.12

Example 1 ($a^n b^n$, $n \geq 0$) — Acceptance

$(q_0, aaabbb, Z_0)$	// $\delta(q_0, a, Z_0) \rightarrow (q_0, Z_0 a)$
$\vdash (q_0, aabbb, Z_0 a)$	// $\delta(q_0, a, Z_0) \rightarrow (q_0, Z_0 a)$
$\vdash (q_0, abbb, Z_0 aa)$	// $\delta(q_0, a, Z_0) \rightarrow (q_0, Z_0 a)$
$\vdash (q_0, bbb, Z_0 aaa)$	// $\delta(q_0, \varepsilon, Z_0) \rightarrow (q_0, \varepsilon)$
$\vdash (q_0, bbb, aaa)$	// $\delta(q_0, b, a) \rightarrow (q_0, \varepsilon)$
$\vdash (q_0, bb, aa)$	// $\delta(q_0, b, a) \rightarrow (q_0, \varepsilon)$
$\vdash (q_0, b, a)$	// $\delta(q_0, b, a) \rightarrow (q_0, \varepsilon)$
$\vdash (q_0, \varepsilon, \varepsilon)$	

1.13

Example 1 ($a^n b^n$, $n \geq 0$) — Failure

$(q_0, aaabbb, Z_0)$	// $\delta(q_0, a, Z_0) \rightarrow (q_0, Z_0 a)$
$\vdash (q_0, abbb, Z_0 a)$	// $\delta(q_0, a, Z_0) \rightarrow (q_0, Z_0 a)$
$\vdash (q_0, bbb, Z_0 aa)$	// $\delta(q_0, \varepsilon, Z_0) \rightarrow (q_0, \varepsilon)$
$\vdash (q_0, bbb, aa)$	// $\delta(q_0, b, a) \rightarrow (q_0, \varepsilon)$
$\vdash (q_0, bb, a)$	// $\delta(q_0, b, a) \rightarrow (q_0, \varepsilon)$
$\vdash (q_0, b, \varepsilon)$	// no rule to be applied

1.14

Example 2 ($ww^R, w \in \{a, b\}^+$) — Definition

$M = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$
 $Q = \{q_0, q_1, q_F\}$ $\Sigma = \{a, b\}$ $\Gamma = \{a, b, Z_0\}$ $F = \{q_F\}$
 δ : $\delta(q_0, a, Z_0) \rightarrow \{(q_0, aZ_0)\}$
 $\delta(q_0, b, Z_0) \rightarrow \{(q_0, bZ_0)\}$
 $\delta(q_0, a, a) \rightarrow \{(q_0, aa), (q_1, \varepsilon)\}$
 $\delta(q_0, a, b) \rightarrow \{(q_0, ab)\}$
 $\delta(q_0, b, a) \rightarrow \{(q_0, ba)\}$
 $\delta(q_0, b, b) \rightarrow \{(q_0, bb), (q_1, \varepsilon)\}$
 $\delta(q_1, b, b) \rightarrow \{(q_1, \varepsilon)\}$
 $\delta(q_1, a, a) \rightarrow \{(q_1, \varepsilon)\}$
 $\delta(q_1, \varepsilon, Z_0) \rightarrow \{(q_F, \varepsilon)\}$

1.15

Example 2 ($ww^R, w \in \{a, b\}^+$) — Acceptance

$(q_0, abbaabba, Z_0)$	// $\delta(q_0, a, Z_0) \rightarrow (q_0, aZ_0)$
$\vdash (q_0, bbaabba, aZ_0)$	// $\delta(q_0, b, a) \rightarrow (q_0, ba)$
$\vdash (q_0, baabba, baZ_0)$	// $\delta(q_0, b, b) \rightarrow (q_0, bb)$
$\vdash (q_0, aabba, bbaZ_0)$	// $\delta(q_0, a, b) \rightarrow (q_0, ab)$
$\vdash (q_0, abba, abbaZ_0)$	// $\delta(q_0, a, a) \rightarrow (q_1, \varepsilon)$
$\vdash (q_1, bba, bbaZ_0)$	// $\delta(q_1, b, b) \rightarrow (q_1, \varepsilon)$
$\vdash (q_1, ba, baZ_0)$	// $\delta(q_1, b, b) \rightarrow (q_1, \varepsilon)$
$\vdash (q_1, a, aZ_0)$	// $\delta(q_1, a, a) \rightarrow (q_1, \varepsilon)$
$\vdash (q_1, \varepsilon, Z_0)$	// $\delta(q_1, \varepsilon, Z_0) \rightarrow (q_F, \varepsilon)$
$\vdash (q_F, \varepsilon, \varepsilon)$	

1.16

Example 2 ($ww^R, w \in \{a, b\}^+$) — Failure

$(q_0, abbaaaba, Z_0)$	// $\delta(q_0, a, Z_0) \rightarrow (q_0, aZ_0)$
$\vdash (q_0, bbaaaba, aZ_0)$	// $\delta(q_0, b, a) \rightarrow (q_0, ba)$
$\vdash (q_0, baaaba, baZ_0)$	// $\delta(q_0, b, b) \rightarrow (q_0, bb)$
$\vdash (q_0, aaaba, bbaZ_0)$	// $\delta(q_0, a, b) \rightarrow (q_0, ab)$
$\vdash (q_0, aaba, abbaZ_0)$	// $\delta(q_0, a, a) \rightarrow (q_1, \varepsilon)$
$\vdash (q_1, aba, bbaZ_0)$	// no rule to be applied

1.17

3 Syntax Analysis with PA

Syntax Analysis—General View

How to construct a PA?

- Directly
- From a context-free grammar

Syntax Analysis

Virtual reconstruction of a particular derivation tree for the given grammar and sentence of the language.

Note: to make difference between end of the input tape and ignoring the input symbol we will use \$ to represent end of the input tape (empty input) and ε to denote that we do not read the symbol under the reading head and the reading head is not moved.

1.18

3.1 Top-Down Analysis

Top-Down Analysis

Virtual reconstruction of the derivation tree starts from the starting non-terminal of the respective context-free grammar.

Construction

Let $G = (N, T, P, S)$ be a context-free grammar then construct $M = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$ this way:

- $Q = \{q_0, q, q_F\}$

- $\Sigma = T \cup \{\$\}$
- $\Gamma = \{Z_0\} \cup T \cup N, \quad \{Z_0, \$\} \cap (T \cup N) = \emptyset$
- $F = \{q_F\}$
- For all $A \rightarrow \alpha \in P, A \in N, \alpha \in (N \cup T)^*$
 - add $(q, \varepsilon, A) \rightarrow \{(q, \alpha)\}$ to δ
- For all $a \in T$ add $(q, a, a) \rightarrow \{(q, \varepsilon)\}$ to δ
- Add $(q_0, \varepsilon, Z_0) \rightarrow \{(q, SZ_0)\}$ to δ
- Add $(q, \$, Z_0) \rightarrow \{(q_F, \varepsilon)\}$ to δ

Example—Construction

CF Grammar

Let $G = (N, T, P, S)$, where: $N = \{S, E\}, T = \{ (,), +, i \}, P = \{ S \rightarrow SS \mid E, E \rightarrow E + E \mid i \mid (E) \}$.

PA Construction

Let $M = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$, where:

- $Q = \{q_0, q, q_F\}, F = \{q_F\}$
- $\Sigma = T \cup \{\$\} = \{ (,), +, i, \$ \}$
- $\Gamma = \{Z_0\} \cup T \cup N = \{S, E, (,), +, i, Z_0\}$
- $\delta(q, \$, Z_0) \rightarrow \{(q_F, \varepsilon)\}$
- $\delta(q_0, \varepsilon, Z_0) \rightarrow \{(q, SZ_0)\}$
- $\delta(q, \varepsilon, S) \rightarrow \{(q, SS), (q, E)\}$
- $\delta(q, \varepsilon, E) \rightarrow \{(q, E + E), (q, i), (q, (E))\}$
- $\delta(q, (, () \rightarrow \{(q, \varepsilon)\}$
- $\delta(q, (,) \rightarrow \{(q, \varepsilon)\}$
- $\delta(q, +, +) \rightarrow \{(q, \varepsilon)\}$
- $\delta(q, i, i) \rightarrow \{(q, \varepsilon)\}$

Example—Analysis

$(q_0, i + i(i), Z_0)$	// $\delta(q_0, \varepsilon, Z_0) \rightarrow (q, SZ_0)$
$\vdash (q, i + i(i), SZ_0)$	// $\delta(q, \varepsilon, S) \rightarrow (q, SS)$
$\vdash (q, i + i(i), SSZ_0)$	// $\delta(q, \varepsilon, S) \rightarrow (q, E)$
$\vdash (q, i + i(i), ESZ_0)$	// $\delta(q, \varepsilon, E) \rightarrow (q, E + E)$
$\vdash (q, i + i(i), E + ESZ_0)$	// $\delta(q, \varepsilon, E) \rightarrow (q, i)$
$\vdash (q, i + i(i), i + ESZ_0)$	// $\delta(q, i, i) \rightarrow (q, \varepsilon)$
$\vdash (q, +i(i), +ESZ_0)$	// $\delta(q, +, +) \rightarrow (q, \varepsilon)$
$\vdash (q, i(i), ESZ_0)$	// $\delta(q, \varepsilon, E) \rightarrow (q, i)$
$\vdash (q, i(i), iSZ_0)$	// $\delta(q, i, i) \rightarrow (q, \varepsilon)$
$\vdash (q, (i), SZ_0)$	// $\delta(q, \varepsilon, S) \rightarrow (q, E)$
$\vdash (q, (i), EZ_0)$	// $\delta(q, \varepsilon, E) \rightarrow (q, (E))$
$\vdash (q, (i), (E)Z_0)$	// $\delta(q, (, () \rightarrow (q, \varepsilon)$
$\vdash (q, (i), E)Z_0)$	// $\delta(q, \varepsilon, E) \rightarrow (q, i)$
$\vdash (q, (i), i)Z_0)$	// $\delta(q, i, i) \rightarrow (q, \varepsilon)$
$\vdash (q, (,)Z_0)$	// $\delta(q, (,) \rightarrow (q, \varepsilon)$
$\vdash (q, \$, Z_0)$	// $\delta(q, \$, Z_0) \rightarrow (q_F, \varepsilon)$
$\vdash (q_F, \$, \varepsilon)$	

Example—Derivation Reconstruction

Grammar “rules” used in the following order:

1. $S \rightarrow SS$
2. $S \rightarrow E$
3. $E \rightarrow E + E$
4. $E \rightarrow i$
5. $E \rightarrow i$
6. $S \rightarrow E$
7. $E \rightarrow (E)$
8. $E \rightarrow i$

It was **left derivation**, thus we get:

$$S \Rightarrow SS \Rightarrow ES \Rightarrow E + ES \Rightarrow i + ES \Rightarrow i + iS \Rightarrow \Rightarrow i + iE \Rightarrow i + i(E) \Rightarrow i + i(i)$$

3.2 Bottom-Up Analysis

Definitions

Bottom-Up Analysis

Reconstruction of the derivation tree starts from the symbols of the input sentence up to the starting non-terminal of the respective grammar.

Definition of Extended PA

An extended pushdown automaton is a seven-tuple $M = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$, where $Q, \Sigma, \Gamma, q_0, Z_0$, and F have the same meaning as for pushdown automaton.

δ is defined as mapping $Q \times (\Sigma \cup \{\varepsilon\}) \times \Gamma^* \rightarrow 2^{Q \times \Gamma^*}$

1.23

Construction

Let $G = (N, T, P, S)$ be a context-free grammar then construct $M = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$ this way:

- $Q = \{q_0, q_1, q_F\}$
- $\Sigma = T \cup \{\$\}$
- $\Gamma = \{Z_0\} \cup T \cup N$
- $F = \{q_F\}$
- For all $A \rightarrow \alpha \in P, A \in N, \alpha \in (N \cup T)^*$
add $(q_0, \varepsilon, \alpha^R) \rightarrow \{(q_0, A)\}$ to δ
- For all $a \in T$ and all $z \in \Gamma$ add $(q_0, a, z) \rightarrow \{(q_0, az)\}$ to δ
- Add $(q_0, \varepsilon, S) \rightarrow \{(q_1, \varepsilon)\}$ to δ
- Add $(q_1, \$, Z_0) \rightarrow \{(q_F, \varepsilon)\}$ to δ

1.24

Example—Construction

CF Grammar

Let $G = (N, T, P, S)$, where: $N = \{S, E\}, T = \{(\,), +, i\}, P = \{S \rightarrow SS \mid E, E \rightarrow E + E \mid i \mid (E)\}$.

PA Construction

Let $M = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$, where:

- $Q = \{q_0, q_1, q_F\}, F = \{q_F\}$
- $\Sigma = T \cup \{\$\} = \{(\,), +, i, \$\}$
- $\Gamma = \{Z_0\} \cup T \cup N = \{S, E, (\,), +, i, Z_0\}$
- $\delta(q_0, \varepsilon, S) \rightarrow \{(q_1, \varepsilon)\}$
- $\delta(q_1, \$, Z_0) \rightarrow \{(q_F, \varepsilon)\}$
- $\delta(q_0, \varepsilon, SS) \rightarrow \{(q_0, S)\}$
- $\delta(q_0, \varepsilon, E) \rightarrow \{(q_0, S)\}$
- $\delta(q_0, \varepsilon, E + E) \rightarrow \{(q_0, E)\}$
- $\delta(q_0, \varepsilon, i) \rightarrow \{(q_0, E)\}$
- $\delta(q_0, \varepsilon, E()) \rightarrow \{(q_0, E)\} \dots$

1.25

Example—Construction

PA Construction

- $\dots \delta(q_0, (\,), Z_0) \rightarrow \{(q_0, (Z_0))\}$
- $\delta(q_0, (\,), Z_0) \rightarrow \{(q_0,)Z_0\}$
- $\delta(q_0, +, Z_0) \rightarrow \{(q_0, +Z_0)\}$
- $\delta(q_0, i, Z_0) \rightarrow \{(q_0, iZ_0)\}$
- $\delta(q_0, (\,), S) \rightarrow \{(q_0, (S))\}$
- $\delta(q_0, (\,), S) \rightarrow \{(q_0,)S\}$
- $\delta(q_0, +, S) \rightarrow \{(q_0, +S)\}$
- $\delta(q_0, i, S) \rightarrow \{(q_0, iS)\}$
- $\delta(q_0, (\,), E) \rightarrow \{(q_0, (E))\}$
- $\delta(q_0, (\,), E) \rightarrow \{(q_0,)E\}$
- $\delta(q_0, +, E) \rightarrow \{(q_0, +E)\}$
- $\delta(q_0, i, E) \rightarrow \{(q_0, iE)\} \dots$

\dots for all $z \in \Gamma$

1.26

Example—Analysis

$(q_0, i + i(i), Z_0)$	$// \delta(q_0, i, Z_0) \rightarrow (q_0, iZ_0)$
$\vdash (q_0, +i(i), iZ_0)$	$// \delta(q_0, \varepsilon, i) \rightarrow (q_0, E)$
$\vdash (q_0, +i(i), EZ_0)$	$// \delta(q_0, +, E) \rightarrow (q_0, +E)$
$\vdash (q_0, i(i), +EZ_0)$	$// \delta(q_0, i, +) \rightarrow (q_0, i+)$
$\vdash (q_0, (i), i + EZ_0)$	$// \delta(q_0, \varepsilon, i) \rightarrow (q_0, E)$
$\vdash (q_0, (i), E + EZ_0)$	$// \delta(q_0, \varepsilon, E + E) \rightarrow (q_0, E)$
$\vdash (q_0, (i), EZ_0)$	$// \delta(q_0, \varepsilon, E) \rightarrow (q_0, S)$
$\vdash (q_0, (i), SZ_0)$	$// \delta(q_0, (, S) \rightarrow (q_0, (S)$
$\vdash (q_0, i), (SZ_0)$	$// \delta(q_0, i, () \rightarrow (q_0, i()$
$\vdash (q_0,), i(SZ_0)$	$// \delta(q_0, \varepsilon, i) \rightarrow (q_0, E)$
$\vdash (q_0,), E(SZ_0)$	$// \delta(q_0,), E) \rightarrow (q_0,)E)$
$\vdash (q_0, $), E(SZ_0)$	$// \delta(q_0, \varepsilon,)E() \rightarrow (q_0, E)$
$\vdash (q_0, $, ESZ_0)$	$// \delta(q_0, \varepsilon, E) \rightarrow (q_0, S)$
$\vdash (q_0, $, SSZ_0)$	$// \delta(q_0, \varepsilon, SS) \rightarrow (q_0, S)$
$\vdash (q_0, $, SZ_0)$	$// \delta(q_0, \varepsilon, S) \rightarrow (q_1, \varepsilon)$
$\vdash (q_1, $, Z_0)$	$// \delta(q_1, $, Z_0) \rightarrow (q_F, \varepsilon)$
$\vdash (q_F, $, \varepsilon)$	

1.27

Example—Derivation Reconstruction

Grammar “rules” used in the following order:

1. $E \rightarrow i$
2. $E \rightarrow i$
3. $E \rightarrow E + E$
4. $S \rightarrow E$
5. $E \rightarrow i$
6. $E \rightarrow (E)$
7. $S \rightarrow E$
8. $S \rightarrow SS$

It was **right derivation** in reverse order, thus we get:

$$S \Rightarrow SS \Rightarrow SE \Rightarrow S(E) \Rightarrow S(i) \Rightarrow E(i) \Rightarrow \Rightarrow E + E(i) \Rightarrow E + i(i) \Rightarrow i + i(i)$$

1.28

4 Deterministic/Non-Deterministic PA

Importance of Determinism

Non-deterministic analysis of context-free languages

- Possible
- With backtracking
- Inefficient

Deterministic analysis of context-free languages

- Possible for certain, but sufficiently large subset of context-free languages
- Without backtracking
- Efficient

1.29

4.1 Non-Deterministic PA

Non-Deterministic Pushdown Automata

Presented definition matches non-deterministic pushdown automata

Where is the non-determinism?

- $\delta(q, a, z) \rightarrow \{(q', \alpha), (q'', \beta), \dots\}$ — multiple choice
- $\delta(q, \varepsilon, z) \rightarrow \{\dots\}$ — ε matches always

All examples presented so far demonstrated non-deterministic pushdown automata

1.30

4.2 Deterministic PA

Deterministic Pushdown Automata

Formal Definition of Deterministic Pushdown Automaton

A deterministic pushdown automaton is a seven-tuple $M = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$, where

- Q — finite set of states
- Σ — finite input alphabet
- Γ — finite alphabet of pushdown symbols
- δ — mapping $Q \times (\Sigma \cup \{\epsilon\}) \times \Gamma \rightarrow Q \times \Gamma^*$ transition function
- $q_0 \in Q$ — starting/initial state
- $Z_0 \in \Gamma$ — start symbol on the pushdown
- $F \subseteq Q$ — set of final states

Configuration, move, final configuration, and accepted language defined the same way

1.31

Deterministic Pushdown Automata

Is the definition sufficient to ensure determinism?

No!

- Eliminated multiple choices,
- but the other option must be eliminated by **proper construction**.
Compare: $\delta(q, a, Z) \rightarrow (p, u)$ versus $\delta(q, \epsilon, Z) = (p', u')$

1.32

Deterministic Pushdown Automata

Is it possible to find deterministic automaton for every non-deterministic one?

Unfortunately, **no!**

- Principal reasons
- Ambiguity of grammar used for automata construction

Let us try ...

1.33

4.3 Examples

Example 1' ($a^n b^n, n \geq 0$) — Introduction

Possible solution features:

- Separation of empty and non-empty input cases
- State for reading of as with duplication to the pushdown
- State for reading of bs when removing symbols from pushdown to check that number of both is equal
- Separate final state — final configuration 3 (empty pushdown & final state)

1.34

Example 1' ($a^n b^n, n \geq 0$) — Definition

$M = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$

$Q = \{q_0, q_1, q_2, q_F\}$ $\Sigma = \{a, b, \$\}$ $\Gamma = \{Z_0\}$ $F = \{q_F\}$

δ : $\delta(q_0, a, Z_0) \rightarrow (q_1, Z_0 Z_0)$
 $\delta(q_1, a, Z_0) \rightarrow (q_1, Z_0 Z_0)$
 $\delta(q_1, b, Z_0) \rightarrow (q_2, \epsilon)$
 $\delta(q_2, b, Z_0) \rightarrow (q_2, \epsilon)$
 $\delta(q_2, \$, Z_0) \rightarrow (q_F, \epsilon)$
 $\delta(q_0, \$, Z_0) \rightarrow (q_F, \epsilon)$

1.35

Example 1' ($a^n b^n, n \geq 0$) — Acceptance

$(q_0, aaabbb, Z_0)$	// $\delta(q_0, a, Z_0) \rightarrow (q_1, Z_0 Z_0)$
$\vdash (q_1, aabbb, Z_0 Z_0)$	// $\delta(q_1, a, Z_0) \rightarrow (q_1, Z_0 Z_0)$
$\vdash (q_1, abbb, Z_0 Z_0 Z_0)$	// $\delta(q_1, a, Z_0) \rightarrow (q_1, Z_0 Z_0)$
$\vdash (q_1, bbb, Z_0 Z_0 Z_0 Z_0)$	// $\delta(q_1, b, Z_0) \rightarrow (q_2, \varepsilon)$
$\vdash (q_2, bb, Z_0 Z_0 Z_0)$	// $\delta(q_2, b, Z_0) \rightarrow (q_2, \varepsilon)$
$\vdash (q_2, b, Z_0 Z_0)$	// $\delta(q_2, b, Z_0) \rightarrow (q_2, \varepsilon)$
$\vdash (q_2, \$, Z_0)$	// $\delta(q_2, \$, Z_0) \rightarrow (q_F, \varepsilon)$
$\vdash (q_F, \$, \varepsilon)$	

1.36

Example 1' ($a^n b^n, n \geq 0$) — Failure

$(q_0, aaabbb, Z_0)$	// $\delta(q_0, a, Z_0) \rightarrow (q_1, Z_0 Z_0)$
$\vdash (q_1, abbb, Z_0 Z_0)$	// $\delta(q_1, a, Z_0) \rightarrow (q_1, Z_0 Z_0)$
$\vdash (q_1, bbb, Z_0 Z_0 Z_0)$	// $\delta(q_1, b, Z_0) \rightarrow (q_2, \varepsilon)$
$\vdash (q_2, bb, Z_0 Z_0)$	// $\delta(q_2, b, Z_0) \rightarrow (q_2, \varepsilon)$
$\vdash (q_2, b, Z_0)$	// $\delta(q_2, b, Z_0) \rightarrow (q_2, \varepsilon)$
$\vdash (q_2, \$, \varepsilon)$	// no rule to be applied

1.37

Example 1' ($a^n b^n, n \geq 0$) — Discussion

Creation possible

No algorithm to transform the non-deterministic PA

Other solutions may work as well *What modification can be done? Can we reduce number of states?*

A non-ambiguous grammar exists $S \rightarrow \varepsilon \mid aSb$ Other features: LL(1)

1.38

Example 2' ($ww^R, w \in \{a, b\}^+$) — Discussion

No deterministic PA exists

Reason: it is impossible to denote the midpoint without additional information deterministically.

A non-ambiguous grammar exists though $S \rightarrow \varepsilon \mid aSa \mid bSb$ Other features: can't be LL(1)

Question: can a deterministic PA be defined for language $wcw^R, w \in \{a, b\}^+$?

1.39

Example 3 — Introduction

Definition based on grammar description of the language: $P = \{ S \rightarrow SS \mid E, E \rightarrow E + E \mid i \mid (E) \}$.

Problem: ambiguous grammar

Consider: $i + i + i$

$S \Rightarrow E \Rightarrow E_1 + E_2 \Rightarrow E_{1.1} + E_{1.2} + E_2 \Rightarrow \dots$

$S \Rightarrow E \Rightarrow E_1 + E_2 \Rightarrow E_1 + E_{2.1} + E_{2.2} \Rightarrow \dots$

We can make it non-ambiguous: $P = \{ S \rightarrow ES', S' \rightarrow \varepsilon \mid ES', E \rightarrow (E)E' \mid iE', E' \rightarrow \varepsilon \mid +E \}$

Does it help? Not for human... but for machine, maybe. We need a modification of PA.

1.40

5 Modifications of PA

Modifications of Pushdown Automata

Purpose:

- new features to make our life easier
- limit features to study properties and simplify analysis
- extend features (regulated PA)

Selected modifications:

- Non-Head-Moving PA
- One-Turn PA
- Atomic PA

1.41

5.1 Non-Head-Moving PA

Head Does Not Move During Reading

Limiting feature: when recognizing symbol under the reading head, the head has to move.

Formal modification of transition function:

$$\delta : Q \times (\Sigma \cup \{\varepsilon\}) \times \Gamma \rightarrow Q \times \Gamma^* \times \{\mathcal{R}, \mathcal{M}\}$$

\mathcal{R} stays for reading the symbol under the reading head only

\mathcal{M} stays for read&move (traditional behaviour)

Notation:

$$\delta(q, a, z) \rightarrow (q', \alpha)_R$$

$$\delta(q, a, z) \rightarrow (q', \alpha)_M \text{ we write } \delta(q, a, z) \rightarrow (q', \alpha) \text{ if clear}$$

where $q, q' \in Q, a \in \Sigma, z \in \Gamma, \alpha \in \Gamma^*$

Generally non-deterministic variant: $\delta : Q \times (\Sigma \cup \{\varepsilon\}) \times \Gamma \rightarrow 2^{Q \times \Gamma^* \times \{\mathcal{R}, \mathcal{M}\}}$

1.42

Example 1" ($a^n b^n, n \geq 0$) — Definition

$$M = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$$

$$Q = \{q_0\} \Sigma = \{a, b, \$\} \Gamma = \{a, b, Z_0\} F = \{q_0\}$$

$$\delta: \delta(q_0, a, Z_0) \rightarrow (q_0, aZ_0b)_R$$

$$\delta(q_0, b, Z_0) \rightarrow (q_0, \varepsilon)_R$$

$$\delta(q_0, a, a) \rightarrow (q_0, \varepsilon)$$

$$\delta(q_0, b, b) \rightarrow (q_0, \varepsilon)$$

$$\delta(q_0, \$, Z_0) \rightarrow (q_0, \varepsilon)$$

Final configuration 3.

1.43

Example 1" ($a^n b^n, n \geq 0$) — Acceptance

$(q_0, aaabbb, Z_0)$	// $\delta(q_0, a, Z_0) \rightarrow (q_0, aZ_0b)_R$
$\vdash (q_0, aaabbb, aZ_0b)$	// $\delta(q_0, a, a) \rightarrow (q_0, \varepsilon)$
$\vdash (q_0, aabbb, Z_0b)$	// $\delta(q_0, a, Z_0) \rightarrow (q_0, aZ_0b)_R$
$\vdash (q_0, aabbb, aZ_0bb)$	// $\delta(q_0, a, a) \rightarrow (q_0, \varepsilon)$
$\vdash (q_0, abbb, Z_0bb)$	// $\delta(q_0, a, Z_0) \rightarrow (q_0, aZ_0b)_R$
$\vdash (q_0, abbb, aZ_0bbb)$	// $\delta(q_0, a, a) \rightarrow (q_0, \varepsilon)$
$\vdash (q_0, bbb, Z_0bbb)$	// $\delta(q_0, b, Z_0) \rightarrow (q_0, \varepsilon)_R$
$\vdash (q_0, bbb, bbb)$	// $\delta(q_0, b, b) \rightarrow (q_0, \varepsilon)$
$\vdash (q_0, bb, bb)$	// $\delta(q_0, b, b) \rightarrow (q_0, \varepsilon)$
$\vdash (q_0, b, b)$	// $\delta(q_0, b, b) \rightarrow (q_0, \varepsilon)$
$\vdash (q_0, \$, \varepsilon)$	

1.44

Example 1" ($a^n b^n, n \geq 0$) — Failure

$(q_0, aabbb, Z_0)$	// $\delta(q_0, a, Z_0) \rightarrow (q_0, aZ_0b)_R$
$\vdash (q_0, aabbb, aZ_0b)$	// $\delta(q_0, a, a) \rightarrow (q_0, \varepsilon)$
$\vdash (q_0, abbb, Z_0b)$	// $\delta(q_0, a, Z_0) \rightarrow (q_0, aZ_0b)_R$
$\vdash (q_0, abbb, aZ_0bb)$	// $\delta(q_0, a, a) \rightarrow (q_0, \varepsilon)$
$\vdash (q_0, bbb, Z_0bb)$	// $\delta(q_0, b, Z_0) \rightarrow (q_0, \varepsilon)_R$
$\vdash (q_0, bbb, bb)$	// $\delta(q_0, b, b) \rightarrow (q_0, \varepsilon)$
$\vdash (q_0, bb, b)$	// $\delta(q_0, b, b) \rightarrow (q_0, \varepsilon)$
$\vdash (q_0, b, \varepsilon)$	// no rule to be applied

1.45

Example 3' — Definition

$$P = \{S \rightarrow ES', S' \rightarrow \varepsilon \mid ES', E \rightarrow (E)E' \mid iE', E' \rightarrow \varepsilon \mid +E\}$$

$$M = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$$

$$Q = \{q_0\} \Sigma = \{+, i, (,), \$\} \Gamma = \{+, i, (,), E, S', E', Z_0\} F = \{q_0\}$$

$$\begin{aligned} \delta: & \delta(q_0, (, Z_0) \rightarrow (q_0, ES')_R \\ & \delta(q_0, i, Z_0) \rightarrow (q_0, ES')_R \\ & \delta(q_0, (, E) \rightarrow (q_0, (E)E')_R \\ & \delta(q_0, i, E) \rightarrow (q_0, iE')_R \\ & \delta(q_0, (, S') \rightarrow (q_0, ES')_R \\ & \delta(q_0, i, S') \rightarrow (q_0, ES')_R \\ & \delta(q_0, \$, S') \rightarrow (q_0, \varepsilon)_R \\ & \dots \end{aligned}$$

1.46

Example 3' — Definition

...

$$\begin{aligned} \delta(q_0, +, E') &\rightarrow (q_0, +E)_R \\ \delta(q_0, (, E') &\rightarrow (q_0, \varepsilon)_R \\ \delta(q_0, (, E') &\rightarrow (q_0, \varepsilon)_R \\ \delta(q_0, i, E') &\rightarrow (q_0, \varepsilon)_R \\ \delta(q_0, \$, E') &\rightarrow (q_0, \varepsilon)_R \\ \delta(q_0, (,)) &\rightarrow (q_0, \varepsilon) \\ \delta(q_0, (, () &\rightarrow (q_0, \varepsilon) \\ \delta(q_0, i, i) &\rightarrow (q_0, \varepsilon) \\ \delta(q_0, +, +) &\rightarrow (q_0, \varepsilon) \end{aligned}$$

1.47

Example 3' — Analysis

$(q_0, i + i(i), Z_0)$	// $\delta(q_0, i, Z_0) \rightarrow (q_0, ES')_R$
$\vdash (q_0, i + i(i), ES')$	// $\delta(q_0, i, E) \rightarrow (q_0, iE')_R$
$\vdash (q_0, i + i(i), iE'S')$	// $\delta(q_0, i, i) \rightarrow (q_0, \varepsilon)$
$\vdash (q_0, +i(i), E'S')$	// $\delta(q_0, +, E') \rightarrow (q_0, +E)_R$
$\vdash (q_0, +i(i), +ES')$	// $\delta(q_0, +, +) \rightarrow (q_0, \varepsilon)$
$\vdash (q_0, i(i), ES')$	// $\delta(q_0, i, E) \rightarrow (q_0, iE')_R$
$\vdash (q_0, i(i), iE'S')$	// $\delta(q_0, i, i) \rightarrow (q_0, \varepsilon)$
$\vdash (q_0, (i), E'S')$	// $\delta(q_0, (, E') \rightarrow (q_0, \varepsilon)_R$
$\vdash (q_0, (i), S')$	// $\delta(q_0, (, S') \rightarrow (q_0, ES')_R$
$\vdash (q_0, (i), ES')$	// $\delta(q_0, (, E) \rightarrow (q_0, (E)E')_R$
$\vdash (q_0, (i), (E)E'S')$	// $\delta(q_0, (, () \rightarrow (q_0, \varepsilon)$
$\vdash (q_0, i), E'E'S')$	// $\delta(q_0, i, E) \rightarrow (q_0, iE')_R$
$\vdash (q_0, i), iE'E'S')$	// $\delta(q_0, i, i) \rightarrow (q_0, \varepsilon)$
$\vdash (q_0, (, E'E'S')$	// $\delta(q_0, (, E') \rightarrow (q_0, \varepsilon)_R$
$\vdash (q_0, (,)E'S')$	// $\delta(q_0, (,)) \rightarrow (q_0, \varepsilon)$
$\vdash (q_0, \$, E'S')$	// $\delta(q_0, \$, E') \rightarrow (q_0, \varepsilon)_R$
$\vdash (q_0, \$, S')$	// $\delta(q_0, \$, S') \rightarrow (q_0, \varepsilon)_R$
$\vdash (q_0, \$, \varepsilon)$	

1.48

Example 3' — Discussion

Grammar features:

- Non-ambiguous
- LL(1)
- Not trivial to construct

How could we construct the PA?

- By straightforward reasoning from the grammar—**too difficult!**
- By algorithm
 - See Aho, Sethi, Ullman: Compilers ... in References
 - LL(1) grammar is an input
 - Non-moving pushdown automaton necessary

1.49

5.2 One-Turn PA

Definition of One-Turn PA

Definition

Consider two consecutive moves made by a pushdown automaton, M . If during the first move M does not shorten its pushdown and during the second move it does, then M makes a turn during the second move. A pushdown automaton is *one-turn* if it makes no more than one turn with its pushdown during any computation starting from an initial configuration.

Theorem

One-turn pushdown automata characterize a family of linear languages. *Proof:* see Harrison ... in References.

1.50

Discussion

Example of one-turn PA—Example 1'

Can we re-construct Examples 1 and 2 to be one-turn? **YES!**

Do it!

Hint: differentiate extension and shortening of pushdown by states, allow just one turn!

1.51

5.3 Atomic PA

Definition of Atomic PA

Definition

Modify δ as a mapping from $Q \times (\Sigma \cup \{\varepsilon\}) \times (\Gamma \cup \{\varepsilon\})$. During a move, an *atomic* pushdown automaton changes a state and, in addition, performs exactly one of the following actions:

1. it pushes a symbol onto the pushdown.e.g. $\delta(q, \varepsilon, \varepsilon) \rightarrow \{(q', a)\}$
2. it pops a symbol from the pushdown.e.g. $\delta(q, \varepsilon, a) \rightarrow \{(q', \varepsilon)\}$
3. it reads an input symbol.e.g. $\delta(q, a, \varepsilon) \rightarrow \{(q', \varepsilon)\}$

1.52

Example 1''' ($a^n b^n, n \geq 0$) — Definition

$M = (Q, \Sigma, \Gamma, \delta, q_0, Z_0, F)$

$Q = \{q_0, q_a, q_{a'}, q_{a''}, q_b, q_F\}$ $\Sigma = \{a, b, \$\}$ $\Gamma = \{b, Z_0\}$ $F = \{q_F\}$

δ : $\delta(q_0, a, \varepsilon) \rightarrow (q_a, \varepsilon)$
 $\delta(q_a, \varepsilon, Z_0) \rightarrow (q_{a'}, \varepsilon)$
 $\delta(q_{a'}, \varepsilon, \varepsilon) \rightarrow (q_{a''}, b)$
 $\delta(q_{a''}, \varepsilon, \varepsilon) \rightarrow (q_0, Z_0)$
 $\delta(q_0, b, \varepsilon) \rightarrow (q_b, \varepsilon)$
 $\delta(q_b, \varepsilon, Z_0) \rightarrow (q_b, \varepsilon)$
 $\delta(q_b, \varepsilon, b) \rightarrow (q_0, \varepsilon)$
 $\delta(q_0, \$, \varepsilon) \rightarrow (q_F, \varepsilon)$
 $\delta(q_F, \varepsilon, Z_0) \rightarrow (q_F, \varepsilon)$

Features: deterministic, atomic \Rightarrow easy to implement

1.53

Example 1''' ($a^n b^n, n \geq 0$) — Acceptance

$(q_0, aabb, Z_0)$	// $\delta(q_0, a, \varepsilon) \rightarrow (q_a, \varepsilon)$
$\vdash (q_a, abb, Z_0)$	// $\delta(q_a, \varepsilon, Z_0) \rightarrow (q_{a'}, \varepsilon)$
$\vdash (q_{a'}, abb, \varepsilon)$	// $\delta(q_{a'}, \varepsilon, \varepsilon) \rightarrow (q_{a''}, b)$
$\vdash (q_{a''}, abb, b)$	// $\delta(q_{a''}, \varepsilon, \varepsilon) \rightarrow (q_0, Z_0)$
$\vdash (q_0, abb, Z_0b)$	// $\delta(q_0, a, \varepsilon) \rightarrow (q_a, \varepsilon)$
$\vdash (q_a, bb, Z_0b)$	// $\delta(q_a, \varepsilon, Z_0) \rightarrow (q_{a'}, \varepsilon)$
$\vdash (q_{a'}, bb, b)$	// $\delta(q_{a'}, \varepsilon, \varepsilon) \rightarrow (q_{a''}, b)$
$\vdash (q_{a''}, bb, bb)$	// $\delta(q_{a''}, \varepsilon, \varepsilon) \rightarrow (q_0, Z_0)$
$\vdash (q_0, bb, Z_0bb)$	// $\delta(q_0, b, \varepsilon) \rightarrow (q_b, \varepsilon)$
$\vdash (q_b, b, Z_0bb)$	// $\delta(q_b, \varepsilon, Z_0) \rightarrow (q_b, \varepsilon)$
$\vdash (q_b, b, bb)$	// $\delta(q_b, \varepsilon, b) \rightarrow (q_0, \varepsilon)$

$\vdash (q_0, b, b)$	// $\delta(q_0, b, \varepsilon) \rightarrow (q_b, \varepsilon)$
$\vdash (q_b, \$, b)$	// $\delta(q_b, \varepsilon, b) \rightarrow (q_0, \varepsilon)$
$\vdash (q_0, \$, \varepsilon)$	// $\delta(q_0, \$, \varepsilon) \rightarrow (q_F, \varepsilon)$
$\vdash (q_F, \$, \varepsilon)$	

1.54

Example 1''' ($a^n b^n, n \geq 0$) — Failure

(q_0, a, Z_0)	// $\delta(q_0, a, \varepsilon) \rightarrow (q_a, \varepsilon)$
$\vdash (q_a, \$, Z_0)$	// $\delta(q_a, \varepsilon, Z_0) \rightarrow (q_{a'}, \varepsilon)$
$\vdash (q_{a'}, \$, \varepsilon)$	// $\delta(q_{a'}, \varepsilon, \varepsilon) \rightarrow (q_{a''}, b)$
$\vdash (q_{a''}, \$, b)$	// $\delta(q_{a''}, \varepsilon, \varepsilon) \rightarrow (q_0, Z_0)$
$\vdash (q_0, \$, Z_0 b)$	// $\delta(q_0, \$, \varepsilon) \rightarrow (q_F, \varepsilon)$
$\vdash (q_F, \$, Z_0 b)$	// $\delta(q_F, \varepsilon, Z_0) \rightarrow (q_F, \varepsilon)$
$\vdash (q_F, \$, b)$	// no rule to be applied

(q_0, b, Z_0)	// $\delta(q_0, b, \varepsilon) \rightarrow (q_b, \varepsilon)$
$\vdash (q_b, \$, Z_0)$	// $\delta(q_b, \varepsilon, Z_0) \rightarrow (q_b, \varepsilon)$
$\vdash (q_b, \$, \varepsilon)$	// no rule to be applied

1.55

Example 1''' ($a^n b^n, n \geq 0$) — Discussion

Easy to implement \neq easy to define (algorithmically)

Quite a lot of steps ...

Automaton without movement of reading head is much more efficient ...

Importance in the formal theory

- simplicity of definition
- minimality of description
- ...

1.56

6 Conclusion

Conclusion

We have presented:

- Definition of pushdown automaton
- Connected terms: configuration, transition step, language accepted by PA
- Deterministic and non-deterministic variant
- Some modifications

Main importance in:

- Analysis of context-free languages
- Theoretical computer science

1.57

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1.58